Richard G. Budynas

J. Keith Nisbett

Shigley's



**Tenth Edition** 

Mechanical Engineering Design

# Shigley's Mechanical Engineering Design

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**Tenth Edition** 

# **Richard G. Budynas**

Professor Emeritus, Kate Gleason College of Engineering, Rochester Institute of Technology

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#### SHIGLEY'S MECHANICAL ENGINEERING DESIGN, TENTH EDITION

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# **Dedication**

To my wife, Joanne, my family, and my late brother, Bill, who advised me to enter the field of mechanical engineering. In many respects, Bill had considerable insight, skill, and inventiveness.

**Richard G. Budynas** 

To my wife, Kim, for her unwavering support.

J. Keith Nisbett

# **Dedication to Joseph Edward Shigley**

**Joseph Edward Shigley (1909–1994)** is undoubtedly one of the most well-known and respected contributors in machine design education. He authored or coauthored eight books, including *Theory of Machines and Mechanisms* (with John J. Uicker, Jr.), and *Applied Mechanics of Materials*. He was coeditor-in-chief of the well-known *Standard Handbook of Machine Design*. He began *Machine Design* as sole author in 1956, and it evolved into *Mechanical Engineering Design*, setting the model for such textbooks. He contributed to the first five editions of this text, along with coauthors Larry Mitchell and Charles Mischke. Uncounted numbers of students across the world got their first taste of machine design with Shigley's textbook, which has literally become a classic. Nearly every mechanical engineer for the past half century has referenced terminology, equations, or procedures as being from "Shigley." McGraw-Hill is honored to have worked with Professor Shigley for more than 40 years, and as a tribute to his lasting contribution to this textbook, its title officially reflects what many have already come to call it—*Shigley's Mechanical Engineering Design*.

Having received a bachelor's degree in Electrical and Mechanical Engineering from Purdue University and a master of science in Engineering Mechanics from the University of Michigan, Professor Shigley pursued an academic career at Clemson College from 1936 through 1954. This led to his position as professor and head of Mechanical Design and Drawing at Clemson College. He joined the faculty of the Department of Mechanical Engineering of the University of Michigan in 1956, where he remained for 22 years until his retirement in 1978.

Professor Shigley was granted the rank of Fellow of the American Society of Mechanical Engineers in 1968. He received the ASME Mechanisms Committee Award in 1974, the Worcester Reed Warner Medal for outstanding contribution to the permanent literature of engineering in 1977, and the ASME Machine Design Award in 1985.

Joseph Edward Shigley indeed made a difference. His legacy shall continue.

# **About the Authors**

**Richard G. Budynas** is Professor Emeritus of the Kate Gleason College of Engineering at Rochester Institute of Technology. He has more than 50 years experience in teaching and practicing mechanical engineering design. He is the author of a McGraw-Hill textbook, *Advanced Strength and Applied Stress Analysis*, Second Edition; and coauthor of a McGraw-Hill reference book, *Roark's Formulas for Stress and Strain*, Eighth Edition. He was awarded the BME of Union College, MSME of the University of Rochester, and the PhD of the University of Massachusetts. He is a licensed Professional Engineer in the state of New York.

**J. Keith Nisbett** is an Associate Professor and Associate Chair of Mechanical Engineering at the Missouri University of Science and Technology. He has more than 30 years of experience with using and teaching from this classic textbook. As demonstrated by a steady stream of teaching awards, including the Governor's Award for Teaching Excellence, he is devoted to finding ways of communicating concepts to the students. He was awarded the BS, MS, and PhD of the University of Texas at Arlington.

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# Preface

# **Objectives**

This text is intended for students beginning the study of mechanical engineering design. The focus is on blending fundamental development of concepts with practical specification of components. Students of this text should find that it inherently directs them into familiarity with both the basis for decisions and the standards of industrial components. For this reason, as students transition to practicing engineers, they will find that this text is indispensable as a reference text. The objectives of the text are to:

- Cover the basics of machine design, including the design process, engineering mechanics and materials, failure prevention under static and variable loading, and characteristics of the principal types of mechanical elements.
- Offer a practical approach to the subject through a wide range of real-world applications and examples.
- Encourage readers to link design and analysis.
- Encourage readers to link fundamental concepts with practical component specification.

## **New to This Edition**

Enhancements and modifications to the tenth edition are described in the following summaries:

 A new Chap. 20, *Geometric Dimensioning and Tolerancing*, has been added to introduce an important topic in machine design. Most of the major manufacturing companies utilize geometric dimensioning and tolerancing (GD&T) as a standardized means of accurately representing machine parts and assemblies for the purposes of design, manufacture, and quality control. Unfortunately, many mechanical engineers do not have sufficient exposure to the notation and concepts of GD&T to interpret the drawings.

During the time when GD&T was becoming most prevalent in manufacturing, many engineering schools were phasing out comprehensive drafting courses in favor of computerized CAD instruction. This was followed by another transition to 3D solid modeling, where the part was drawn with ideal dimensions. Unfortunately, this ability to draw a perfect part in three dimensions is all too often accompanied by a neglect of focus on how to accurately and uniquely represent the part for manufacture and inspection.

A full understanding of GD&T is usually obtained through an intensive course or training program. Some mechanical engineers will benefit from such a rigorous training. *All* mechanical engineers, however, should be familiar with the basic concepts and notation. The purpose of the coverage of GD&T in this new chapter is to provide this foundational exposure that is essential for all machine designers.

It is always a challenge to find time to include additional material in a course. To facilitate this, the chapter is arranged and presented at a level appropriate for students

to learn in an independent study format. The problems at the end of the chapter are more like quiz questions, and are focused on checking comprehension of the most fundamental concepts. Instructors are encouraged to consider using this chapter as a reading assignment, coupled with even a minimal lecture or online discussion. Of course, there is ample material for expanded presentation and discussion as well.

- Chapter 1, *Introduction to Mechanical Engineering Design*, has been expanded to provide more insight into design practices. Further discussion of the development of the *design factor* is presented, as well as the statistical relationships between *reliability* and the *probability of failure*, and reliability and the design factor. Statistical considerations are provided here rather than in a chapter at the end of the text as in past editions. The section on Dimensions and Tolerances has been expanded to emphasize the designer's role in specifying dimensions and tolerances as a critical part of machine design.
- The chapter of the previous edition, *Statistical Considerations*, has been eliminated. However, the material of that chapter pertinent to this edition has been integrated within the sections that utilize statistics. The stand-alone section on stochastic methods in Chap. 6, *Fatigue Failure Resulting from Variable Loading*, has also been eliminated. This is based on user input and the authors' convictions that the excessive amount of development and data provided in that section was far too involved for the simple class of problems that could be solved. For instructors who still want access to this material, it is available on McGraw-Hill's Online Learning Center at www.mhhe.com/shigley.
- In Chap. 11, *Rolling-Contact Bearings*, the Weibull probability distribution is defined and related to bearing life.
- In conjunction with the Connect Engineering resource, the end-of-chapter problems have been freshly examined to ensure they are clearly stated with less room for vague interpretations. Approximately 50 percent of the problems are targeted for Connect implementation. With the problem parameterization available in this Web-based platform, students can be assigned basic problems with minimal duplication from student to student and semester to semester. For a good balance, this edition maintains many end-of-chapter problems that are open-ended and suitable for exploration and design.

# connect

# **Connect Engineering**

The tenth edition continues to feature McGraw-Hill Connect Engineering, a Webbased assignment and assessment platform that allows instructors to deliver assignments, quizzes, and tests easily online. Students can practice important skills at their own pace and on their own schedule.

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How does SmartBook work? Each SmartBook contains four components: Preview, Read, Practice, and Recharge. Starting with an initial preview of each chapter and key learning objectives, students read the material and are guided to topics for which they need the most practice based on their responses to a continuously adapting diagnostic. Read and practice continue until SmartBook directs students to recharge important material they are most likely to forget to ensure concept mastery and retention.

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Additional media offerings available at www.mhhe.com/shigley include:

#### **Student Supplements**

• *Fundamentals of Engineering (FE) exam questions for machine design.* Interactive problems and solutions serve as effective, self-testing problems as well as excellent preparation for the FE exam.

#### Instructor Supplements (under password protection)

- *Solutions manual.* The instructor's manual contains solutions to most end-of-chapter nondesign problems.
- *PowerPoint<sup>®</sup> slides*. Slides outlining the content of the text are provided in Power-Point format for instructors to use as a starting point for developing lecture presentation materials. The slides include all figures, tables, and equations from the text.
- *C.O.S.M.O.S.* A complete online solutions manual organization system that allows instructors to create custom homework, quizzes, and tests using end-of-chapter problems from the text.

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# List of Symbols

This is a list of common symbols used in machine design and in this book. Specialized use in a subject-matter area often attracts fore and post subscripts and superscripts. To make the table brief enough to be useful, the symbol kernels are listed. See Table 14–1, pp. 727–728 for spur and helical gearing symbols, and Table 15–1, pp. 781–782 for bevel-gear symbols.

A	Area, coefficient
a	Distance
В	Coefficient
Bhn	Brinell hardness
b	Distance, Weibull shape parameter, range number, width
С	Basic load rating, bolted-joint constant, center distance, coefficient of variation, column end condition, correction factor, specific heat capacity, spring index
С	Distance, viscous damping, velocity coefficient
COV	Coefficient of variation
D	Diameter, helix diameter
d	Diameter, distance
Ε	Modulus of elasticity, energy, error
е	Distance, eccentricity, efficiency, Naperian logarithmic base
F	Force, fundamental dimension force
f	Coefficient of friction, frequency, function
fom	Figure of merit
G	Torsional modulus of elasticity
8	Acceleration due to gravity, function
Н	Heat, power
$H_B$	Brinell hardness
HRC	Rockwell C-scale hardness
h	Distance, film thickness
$\hbar_{CR}$	Combined overall coefficient of convection and radiation heat transfer
Ι	Integral, linear impulse, mass moment of inertia, second moment of area
i	Index
i	Unit vector in x-direction
J	Mechanical equivalent of heat, polar second moment of area, geometry
	factor
j	Unit vector in the y-direction
Κ	Service factor, stress-concentration factor, stress-augmentation factor, torque coefficient
k	Marin endurance limit modifying factor spring rate
k	Unit vector in the z-direction
L	Length life fundamental dimension length
-	

L	Life in hours
l	Length
M	Fundamental dimension mass, moment
Μ	Moment vector
т	Mass, slope, strain-strengthening exponent
Ν	Normal force, number, rotational speed, number of cycles
п	Load factor, rotational speed, factor of safety
$n_d$	Design factor
Р	Force, pressure, diametral pitch
PDF	Probability density function
р	Pitch, pressure, probability
Q	First moment of area, imaginary force, volume
q	Distributed load, notch sensitivity
R	Radius, reaction force, reliability, Rockwell hardness, stress ratio, reduc-
	tion in area
R	Vector reaction force
r	Radius
r	Distance vector
S	Sommerfeld number, strength
S	Distance, sample standard deviation, stress
T	Temperature, tolerance, torque, fundamental dimension time
Т	Torque vector
t T	Distance, time, tolerance
U	Strain energy
u V	Linear velocity, shear force
V 2V	Linear velocity, shear force
W	Cold-work factor load weight
20	Distance gan load intensity
X	Coordinate, truncated number
x	Coordinate, true value of a number. Weibull parameter
Y	Coordinate
v	Coordinate, deflection
Z	Coordinate, section modulus, viscosity
z	Coordinate, dimensionless transform variable for normal distributions
α	Coefficient, coefficient of linear thermal expansion, end-condition for
	springs, thread angle
β	Bearing angle, coefficient
$\Delta$	Change, deflection
δ	Deviation, elongation
$\epsilon$	Eccentricity ratio, engineering (normal) strain
3	True or logarithmic normal strain
Γ	Gamma function, pitch angle
γ	Pitch angle, shear strain, specific weight
λ	Slenderness ratio for springs
$\mu$	Absolute viscosity, population mean
ν	Poisson ratio
ω	Angular velocity, circular frequency
$\phi$	Angle, wave length

- Slope integral ψ
- Radius of curvature, mass density  $\rho$
- $\sigma$ Normal stress
- $\sigma'$ Von Mises stress
- $\hat{\sigma}$ Standard deviation
- Shear stress au
- Angle, Weibull characteristic parameter  $\theta$
- Cost per unit weight
- ¢ \$ Cost

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# Shigley's Mechanical Engineering Design



# Introduction to Mechanical Engineering Design

# **Chapter Outline**

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Mechanical design is a complex process, requiring many skills. Extensive relationships need to be subdivided into a series of simple tasks. The complexity of the process requires a sequence in which ideas are introduced and iterated.

We first address the nature of design in general, and then mechanical engineering design in particular. Design is an iterative process with many interactive phases. Many resources exist to support the designer, including many sources of information and an abundance of computational design tools. Design engineers need not only develop competence in their field but they must also cultivate a strong sense of responsibility and professional work ethic.

There are roles to be played by codes and standards, ever-present economics, safety, and considerations of product liability. The survival of a mechanical component is often related through stress and strength. Matters of uncertainty are ever-present in engineering design and are typically addressed by the design factor and factor of safety, either in the form of a deterministic (absolute) or statistical sense. The latter, statistical approach, deals with a design's *reliability* and requires good statistical data.

In mechanical design, other considerations include dimensions and tolerances, units, and calculations.

This book consists of four parts. Part 1, *Basics*, begins by explaining some differences between design and analysis and introducing some fundamental notions and approaches to design. It continues with three chapters reviewing material properties, stress analysis, and stiffness and deflection analysis, which are the principles necessary for the remainder of the book.

Part 2, *Failure Prevention*, consists of two chapters on the prevention of failure of mechanical parts. Why machine parts fail and how they can be designed to prevent failure are difficult questions, and so we take two chapters to answer them, one on preventing failure due to static loads, and the other on preventing fatigue failure due to time-varying, cyclic loads.

In Part 3, *Design of Mechanical Elements*, the concepts of Parts 1 and 2 are applied to the analysis, selection, and design of specific mechanical elements such as shafts, fasteners, weldments, springs, rolling contact bearings, film bearings, gears, belts, chains, and wire ropes.

Part 4, *Special Topics*, provides introductions to two important methods used in mechanical design, finite element analysis and geometric dimensioning and tolerancing. This is optional study material, but some sections and examples in Parts 1 to 3 demonstrate the use of these tools.

There are two appendixes at the end of the book. Appendix A contains many useful tables referenced throughout the book. Appendix B contains answers to selected end-of-chapter problems.

### 1–1 Design

To design is either to formulate a plan for the satisfaction of a specified need or to solve a specific problem. If the plan results in the creation of something having a physical reality, then the product must be functional, safe, reliable, competitive, usable, manufacturable, and marketable.

Design is an innovative and highly iterative process. It is also a decision-making process. Decisions sometimes have to be made with too little information, occasionally with just the right amount of information, or with an excess of partially contradictory information. Decisions are sometimes made tentatively, with the right reserved to

adjust as more becomes known. The point is that the engineering designer has to be personally comfortable with a decision-making, problem-solving role.

Design is a communication-intensive activity in which both words and pictures are used, and written and oral forms are employed. Engineers have to communicate effectively and work with people of many disciplines. These are important skills, and an engineer's success depends on them.

A designer's personal resources of creativeness, communicative ability, and problemsolving skill are intertwined with the knowledge of technology and first principles. Engineering tools (such as mathematics, statistics, computers, graphics, and languages) are combined to produce a plan that, when carried out, produces a product that is *functional, safe, reliable, competitive, usable, manufacturable, and marketable,* regardless of who builds it or who uses it.

# 1-2 Mechanical Engineering Design

Mechanical engineers are associated with the production and processing of energy and with providing the means of production, the tools of transportation, and the techniques of automation. The skill and knowledge base are extensive. Among the disciplinary bases are mechanics of solids and fluids, mass and momentum transport, manufacturing processes, and electrical and information theory. Mechanical engineering design involves all the disciplines of mechanical engineering.

Real problems resist compartmentalization. A simple journal bearing involves fluid flow, heat transfer, friction, energy transport, material selection, thermomechanical treatments, statistical descriptions, and so on. A building is environmentally controlled. The heating, ventilation, and air-conditioning considerations are sufficiently specialized that some speak of heating, ventilating, and air-conditioning design as if it is separate and distinct from mechanical engineering design. Similarly, internalcombustion engine design, turbomachinery design, and jet-engine design are sometimes considered discrete entities. Here, the leading string of words preceding the word design is merely a product descriptor. Similarly, there are phrases such as machine design, machine-element design, machine-component design, systems design, and fluid-power design. All of these phrases are somewhat more focused *examples* of mechanical engineering design. They all draw on the same bodies of knowledge, are similarly organized, and require similar skills.

# 1-3 Phases and Interactions of the Design Process

What is the design process? How does it begin? Does the engineer simply sit down at a desk with a blank sheet of paper and jot down some ideas? What happens next? What factors influence or control the decisions that have to be made? Finally, how does the design process end?

The complete design process, from start to finish, is often outlined as in Fig. 1–1. The process begins with an identification of a need and a decision to do something about it. After many iterations, the process ends with the presentation of the plans for satisfying the need. Depending on the nature of the design task, several design phases may be repeated throughout the life of the product, from inception to termination. In the next several subsections, we shall examine these steps in the design process in detail.

*Identification of need* generally starts the design process. Recognition of the need and phrasing the need often constitute a highly creative act, because the need may be

#### Figure 1-1

The phases in design, acknowledging the many feedbacks and iterations.



only a vague discontent, a feeling of uneasiness, or a sensing that something is not right. The need is often not evident at all; recognition can be triggered by a particular adverse circumstance or a set of random circumstances that arises almost simultaneously. For example, the need to do something about a food-packaging machine may be indicated by the noise level, by a variation in package weight, and by slight but perceptible variations in the quality of the packaging or wrap.

There is a distinct difference between the statement of the need and the definition of the problem. The *definition of problem* is more specific and must include all the specifications for the object that is to be designed. The specifications are the input and output quantities, the characteristics and dimensions of the space the object must occupy, and all the limitations on these quantities. We can regard the object to be designed as something in a black box. In this case we must specify the inputs and outputs of the box, together with their characteristics and limitations. The specifications define the cost, the number to be manufactured, the expected life, the range, the operating temperature, and the reliability. Specified characteristics can include the speeds, feeds, temperature limitations, maximum range, expected variations in the variables, dimensional and weight limitations, etc.

There are many implied specifications that result either from the designer's particular environment or from the nature of the problem itself. The manufacturing processes that are available, together with the facilities of a certain plant, constitute restrictions on a designer's freedom, and hence are a part of the implied specifications. It may be that a small plant, for instance, does not own cold-working machinery. Knowing this, the designer might select other metal-processing methods that can be performed in the plant. The labor skills available and the competitive situation also constitute implied constraints. Anything that limits the designer's freedom of choice is a constraint. Many materials and sizes are listed in supplier's catalogs, for instance, but these are not all easily available and shortages frequently occur. Furthermore, inventory economics requires that a manufacturer stock a minimum number of materials and sizes. An example of a specification is given in Sec. 1–18. This example is for a case study of a power transmission that is presented throughout this text.

The *synthesis* of a scheme connecting possible system elements is sometimes called the *invention of the concept* or *concept design*. This is the first and most important

step in the synthesis task. Various schemes must be proposed, investigated, and quantified in terms of established metrics.<sup>1</sup> As the fleshing out of the scheme progresses, analyses must be performed to assess whether the system performance is satisfactory or better, and, if satisfactory, just how well it will perform. System schemes that do not survive analysis are revised, improved, or discarded. Those with potential are optimized to determine the best performance of which the scheme is capable. Competing schemes are compared so that the path leading to the most competitive product can be chosen. Figure 1–1 shows that synthesis and *analysis and optimization* are intimately and iteratively related.

We have noted, and we emphasize, that design is an iterative process in which we proceed through several steps, evaluate the results, and then return to an earlier phase of the procedure. Thus, we may synthesize several components of a system, analyze and optimize them, and return to synthesis to see what effect this has on the remaining parts of the system. For example, the design of a system to transmit power requires attention to the design and selection of individual components (e.g., gears, bearings, shaft). However, as is often the case in design, these components are not independent. In order to design the shaft for stress and deflection, it is necessary to know the applied forces. If the forces are transmitted through gears, it is necessary to know the gear specifications in order to determine the forces that will be transmitted to the shaft. But stock gears come with certain bore sizes, requiring knowledge of the necessary shaft diameter. Clearly, rough estimates will need to be made in order to proceed through the process, refining and iterating until a final design is obtained that is satisfactory for each individual component as well as for the overall design specifications. Throughout the text we will elaborate on this process for the case study of a power transmission design.

Both analysis and optimization require that we construct or devise abstract models of the system that will admit some form of mathematical analysis. We call these models mathematical models. In creating them it is our hope that we can find one that will simulate the real physical system very well. As indicated in Fig. 1–1, *evaluation* is a significant phase of the total design process. Evaluation is the final proof of a successful design and usually involves the testing of a prototype in the laboratory. Here we wish to discover if the design really satisfies the needs. Is it reliable? Will it compete successfully with similar products? Is it economical to manufacture and to use? Is it easily maintained and adjusted? Can a profit be made from its sale or use? How likely is it to result in product-liability lawsuits? And is insurance easily and cheaply obtained? Is it likely that recalls will be needed to replace defective parts or systems? The project designer or design team will need to address a myriad of engineering and non-engineering questions.

Communicating the design to others is the final, vital *presentation* step in the design process. Undoubtedly, many great designs, inventions, and creative works have been lost to posterity simply because the originators were unable or unwilling to properly explain their accomplishments to others. Presentation is a selling job. The engineer, when presenting a new solution to administrative, management, or supervisory persons, is attempting to sell or to prove to them that their solution is a better one. Unless this can be done successfully, the time and effort spent on obtaining the

<sup>&</sup>lt;sup>1</sup>An excellent reference for this topic is presented by Stuart Pugh, *Total Design—Integrated Methods for Successful Product Engineering*, Addison-Wesley, 1991. A description of the *Pugh method* is also provided in Chap. 8, David G. Ullman, *The Mechanical Design Process*, 3rd ed., McGraw-Hill, 2003.

solution have been largely wasted. When designers sell a new idea, they also sell themselves. If they are repeatedly successful in selling ideas, designs, and new solutions to management, they begin to receive salary increases and promotions; in fact, this is how anyone succeeds in his or her profession.

#### **Design Considerations**

Sometimes the strength required of an element in a system is an important factor in the determination of the geometry and the dimensions of the element. In such a situation we say that strength is an important *design consideration*. When we use the expression design consideration, we are referring to some characteristic that influences the design of the element or, perhaps, the entire system. Usually quite a number of such characteristics must be considered and prioritized in a given design situation. Many of the important ones are as follows (not necessarily in order of importance):

- **1** Functionality
- 2 Strength/stress
- 3 Distortion/deflection/stiffness
- 4 Wear
- 5 Corrosion
- 6 Safety
- 7 Reliability
- 8 Manufacturability
- 9 Utility
- 10 Cost
- **11** Friction
- 12 Weight13 Life

- 14 Noise15 Styling
- 16 Shape
- 17 Size
- 18 Control
- **19** Thermal properties
- 20 Surface
- 21 Lubrication
- 22 Marketability
- 23 Maintenance
- 24 Volume
- **25** Liability
- **26** Remanufacturing/resource recovery

Some of these characteristics have to do directly with the dimensions, the material, the processing, and the joining of the elements of the system. Several characteristics may be interrelated, which affects the configuration of the total system.

#### 1-4 **Design Tools and Resources**

Today, the engineer has a great variety of tools and resources available to assist in the solution of design problems. Inexpensive microcomputers and robust computer software packages provide tools of immense capability for the design, analysis, and simulation of mechanical components. In addition to these tools, the engineer always needs technical information, either in the form of basic science/engineering behavior or the characteristics of specific off-the-shelf components. Here, the resources can range from science/engineering textbooks to manufacturers' brochures or catalogs. Here too, the computer can play a major role in gathering information.<sup>2</sup>

#### **Computational Tools**

Computer-aided design (CAD) software allows the development of three-dimensional (3-D) designs from which conventional two-dimensional orthographic views with

<sup>&</sup>lt;sup>2</sup>An excellent and comprehensive discussion of the process of "gathering information" can be found in Chap. 4, George E. Dieter, *Engineering Design, A Materials and Processing Approach*, 3rd ed., McGraw-Hill, New York, 2000.

automatic dimensioning can be produced. Manufacturing tool paths can be generated from the 3-D models, and in some cases, parts can be created directly from a 3-D database by using a rapid prototyping and manufacturing method (stereolithography)— *paperless manufacturing!* Another advantage of a 3-D database is that it allows rapid and accurate calculations of mass properties such as mass, location of the center of gravity, and mass moments of inertia. Other geometric properties such as areas and distances between points are likewise easily obtained. There are a great many CAD software packages available such as Aries, AutoCAD, CadKey, I-Deas, Unigraphics, Solid Works, and ProEngineer, to name a few.

The term *computer-aided engineering* (CAE) generally applies to all computerrelated engineering applications. With this definition, CAD can be considered as a subset of CAE. Some computer software packages perform specific engineering analysis and/or simulation tasks that assist the designer, but they are not considered a tool for the creation of the design that CAD is. Such software fits into two categories: engineering-based and non-engineering-specific. Some examples of engineering-based software for mechanical engineering applications—software that might also be integrated within a CAD system—include finite-element analysis (FEA) programs for analysis of stress and deflection (see Chap. 19), vibration, and heat transfer (e.g., Algor, ANSYS, and MSC/NASTRAN); computational fluid dynamics (CFD) programs for fluid-flow analysis and simulation (e.g., CFD++, FIDAP, and Fluent); and programs for simulation of dynamic force and motion in mechanisms (e.g., ADAMS, DADS, and Working Model).

Examples of non-engineering-specific computer-aided applications include software for word processing, spreadsheet software (e.g., Excel, Lotus, and Quattro-Pro), and mathematical solvers (e.g., Maple, MathCad, MATLAB,<sup>3</sup> Mathematica, and TKsolver).

Your instructor is the best source of information about programs that may be available to you and can recommend those that are useful for specific tasks. One caution, however: Computer software is no substitute for the human thought process. *You* are the driver here; the computer is the vehicle to assist you on your journey to a solution. Numbers generated by a computer can be far from the truth if you entered incorrect input, if you misinterpreted the application or the output of the program, if the program contained bugs, etc. It is your responsibility to assure the validity of the results, so be careful to check the application and results carefully, perform benchmark testing by submitting problems with known solutions, and monitor the software company and user-group newsletters.

#### **Acquiring Technical Information**

We currently live in what is referred to as the *information age*, where information is generated at an astounding pace. It is difficult, but extremely important, to keep abreast of past and current developments in one's field of study and occupation. The reference in footnote 2 provides an excellent description of the informational resources available and is highly recommended reading for the serious design engineer. Some sources of information are:

 Libraries (community, university, and private). Engineering dictionaries and encyclopedias, textbooks, monographs, handbooks, indexing and abstract services, journals, translations, technical reports, patents, and business sources/brochures/catalogs.

<sup>&</sup>lt;sup>3</sup>MATLAB is a registered trademark of The MathWorks, Inc.